

## PLSD-6030 Brushless Low-voltage Servo Drive

The PLSD-6030 low-voltage servo driver is developed with a high-performance processor to provide users with a cost-effective servo control solution. On the premise of ensuring stability and reliability, it pursues the functions and performance that are closest to the application. Compared with stepping products, it has low noise, low heat generation, high speed, constant torque output, and no step loss; compared with stepping servo products, it completely abandons the inherent disadvantages of stepping products, and has better functions, performance and reliability. Excellent; compared with well-known foreign servos, the performance is similar, the price is low, and it is easy to use. PLSD-6030 is a function and power enhanced version of PLSD-6020, with high cost performance and reliability, suitable for applications with various control methods.

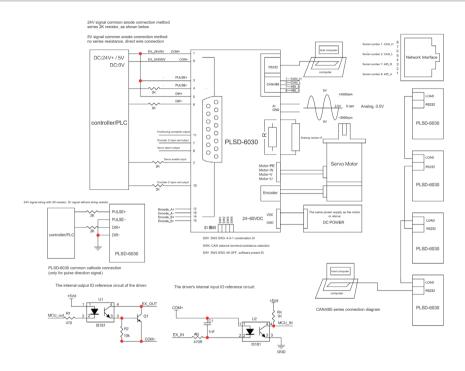
#### **Characteristics**

- Working Voltage: 24~60VDC
- Output Current: peak 30A
- Adapter motor: 5~750W low voltage DC servo motor
- Control mode: external pulse (single-ended/differential), analog, CANBUS, RS485 bus, RS232 communication control IO control, etc., support position, speed and torque mode
- Parameter Debugging: use RS232 communication, PC debugging software or hand-held debugger debugging can backup and import parameters
- Abnormal Protection: with under-voltage, over-voltage, over-load over-current, excessive position deviation encoder abnormality and other protection alarm functions
- Support energy consumption discharge function
- Tracking error: ±1pulse
- Speed Control Accuracy: ±1PRM
- Receive Pulse Upper Limit: 1MHZ
- Minimum Speed: 1RPM
- Maximum No-load Acceleration: 200PRM/ms

#### **Specifications**

Model	Peak current (A)	Voltage (VDC)	Matched Motor	Dimension (mm)	Control Signal
PLSD-6030	30	24~60	Low Voltage Servo Motor (700W and below)	120.6*76.8*35.4	Pulse (Single-Ended/Differential)/ Analog/ CANBUS/ RS485 bus/ RS232/ IO

#### **Wiring Diagram**



#### **Dimension**

# 129 0 76.8 8.92 0 35.4 120.6

### **Interface Diagram**

